

6.2 Roof Monitor Air Sampling System.

6.2.1 Manifold System and Ductwork. A minimum of one manifold system shall be installed for each potroom group. The manifold system and ductwork shall meet the following specifications:

6.2.1.1 The manifold system and connecting duct shall be permanently installed to draw an air sample from the roof monitor to ground level. A typical installation of a duct for drawing a sample from a roof monitor to ground level is shown in Figure 14-1 in Section 17.0. A plan of a manifold system that is located in a roof monitor is shown in Figure 14-2. These drawings represent a typical installation for a generalized roof monitor. The dimensions on these figures may be altered slightly to make the manifold system fit into a particular roof monitor, but the general configuration shall be followed.

6.2.1.2 There shall be eight nozzles, each having a diameter of 0.40 to 0.50 m.

6.2.1.3 The length of the manifold system from the first nozzle to the eighth shall be 35 m (115 ft) or eight percent of the length of the potroom (or potroom segment) roof monitor, whichever is greater. Deviation from this requirement is subject to the approval of the Administrator.

6.2.1.4 The duct leading from the roof monitor manifold system shall be round with a diameter of 0.30 to 0.40 m (1.0 to 1.3 ft). All connections in the ductwork shall be leak-free.

6.2.1.5 As shown in Figure 14-2, each of the sample legs of the manifold shall have a device, such as a blast gate or valve, to enable adjustment of the flow into each sample nozzle.

6.2.1.6 The manifold system shall be located in the immediate vicinity of one of the propeller anemometers (see Section 8.1.1.4) and as close as possible to the midsection of the potroom (or potroom segment). Avoid locating the manifold system near the end of a potroom or in a section where the aluminum reduction pot arrangement is not typical of the rest of the potroom (or potroom segment). The sample nozzles shall be centered in the throat of the roof monitor (see Figure 14-1).

6.2.1.7 All sample-exposed surfaces within the nozzles, manifold, and sample duct shall be constructed with 316 stainless steel. Alternatively, aluminum may be used if a new ductwork is conditioned with fluoride-laden roof monitor air for a period of six weeks before initial testing. Other materials of construction may be used if it is demonstrated through comparative testing, to the satisfaction of the Administrator, that there is no loss of fluorides in the system.

6.2.1.8 Two sample ports shall be located in a vertical section of the duct between the roof monitor and the exhaust fan (see Section 6.2.2). The sample ports shall be at least 10 duct diameters downstream and three di-

ameters upstream from any flow disturbance such as a bend or contraction. The two sample ports shall be situated 90° apart. One of the sample ports shall be situated so that the duct can be traversed in the plane of the nearest upstream duct bend.

6.2.2 Exhaust Fan. An industrial fan or blower shall be attached to the sample duct at ground level (see Figure 14-1). This exhaust fan shall have a capacity such that a large enough volume of air can be pulled through the ductwork to maintain an isokinetic sampling rate in all the sample nozzles for all flow rates normally encountered in the roof monitor. The exhaust fan volumetric flow rate shall be adjustable so that the roof monitor gases can be drawn isokinetically into the sample nozzles. This control of flow may be achieved by a damper on the inlet to the exhauster or by any other workable method.

6.3 Temperature Measurement Apparatus. To monitor and record the temperature of the roof monitor effluent gas, and consisting of the following:

6.3.1 Temperature Sensor. A temperature sensor shall be installed in the roof monitor near the sample duct. The temperature sensor shall conform to the specifications outlined in Method 2, Section 6.3.

6.3.2 Signal Transducer. Transducer, to change the temperature sensor voltage output to a temperature readout.

6.3.3 Thermocouple Wire. To reach from roof monitor to signal transducer and recorder.

6.3.4 Recorder. Suitable recorder to monitor the output from the thermocouple signal transducer.

7.0 Reagents and Standards

Same as Section 7.0 of either Method 13A or Method 13B, as applicable.

8.0 Sample Collection, Preservation, Storage, and Transport

8.1 Roof Monitor Velocity Determination.

8.1.1 Velocity Estimate(s) for Setting Isokinetic Flow. To assist in setting isokinetic flow in the manifold sample nozzles, the anticipated average velocity in the section of the roof monitor containing the sampling manifold shall be estimated before each test run. Any convenient means to make this estimate may be used (*e.g.*, the velocity indicated by the anemometer in the section of the roof monitor containing the sampling manifold may be continuously monitored during the 24-hour period before the test run). If there is question as to whether a single estimate of average velocity is adequate for an entire test run (*e.g.*, if velocities are anticipated to be significantly different during different potroom operations), the test run may be divided into two

or more “sub-runs,” and a different estimated average velocity may be used for each sub-run (see Section 8.4.2).

8.1.2 Velocity Determination During a Test Run. During the actual test run, record the velocity or volumetric flowrate readings of each propeller anemometer in the roof monitor. Readings shall be taken from each anemometer at equal time intervals of 15 minutes or less (or continuously).

8.2 Temperature Recording. Record the temperature of the roof monitor effluent gases at least once every 2 hours during the test run.

8.3 Pretest Ductwork Conditioning. During the 24-hour period immediately preceding the test run, turn on the exhaust fan, and draw roof monitor air through the manifold system and ductwork. Adjust the fan to draw a volumetric flow through the duct such that the velocity of gas entering the manifold nozzles approximates the average velocity of the air exiting the roof monitor in the vicinity of the sampling manifold.

8.4 Manifold Isokinetic Sample Rate Adjustment(s).

8.4.1 Initial Adjustment. Before the test run (or first sub-run, if applicable; see Sections 8.1.1 and 8.4.2), adjust the fan such that air enters the manifold sample nozzles at a velocity equal to the appropriate estimated average velocity determined under Section 8.1.1. Use Equation 14–1 (Section 12.2.2) to determine the correct stream velocity needed in the duct at the sampling location, in order for sample gas to be drawn isokinetically into the manifold nozzles. Next, verify that the correct stream velocity has been achieved, by performing a pitot tube traverse of the sample duct (using either a standard or Type S pitot tube); use the procedure outlined in Method 2.

8.4.2 Adjustments During Run. If the test run is divided into two or more “sub-runs”

(see Section 8.1.1), additional isokinetic rate adjustment(s) may become necessary during the run. Any such adjustment shall be made just before the start of a sub-run, using the procedure outlined in Section 8.4.1 above.

NOTE: Isokinetic rate adjustments are not permissible during a sub-run.

8.5 Pretest Preparation, Preliminary Determinations, Preparation of Sampling Train, Leak-Check Procedures, Sampling Train Operation, and Sample Recovery. Same as Method 13A, Sections 8.1 through 8.6, with the exception of the following:

8.5.1 A single train shall be used for the entire sampling run. Alternatively, if two or more sub-runs are performed, a separate train may be used for each sub-run; note, however, that if this option is chosen, the area of the sampling nozzle shall be the same (± 2 percent) for each train. If the test run is divided into sub-runs, a complete traverse of the duct shall be performed during each sub-run.

8.5.2 Time Per Run. Each test run shall last 8 hours or more; if more than one run is to be performed, all runs shall be of approximately the same (± 10 percent) length. If questions exist as to the representativeness of an 8-hour test, a longer period should be selected. Conduct each run during a period when all normal operations are performed underneath the sampling manifold. For most recently-constructed plants, 24 hours are required for all potroom operations and events to occur in the area beneath the sampling manifold. During the test period, all pots in the potroom group shall be operated such that emissions are representative of normal operating conditions in the potroom group.

9.0 Quality Control

9.1 Miscellaneous Quality Control Measures.

Section	Quality Control Measure	Effect
8.0, 10.0	Sampling equipment leak-check and calibration.	Ensure accurate measurement of gas flow rate in duct and of sample volume.
10.3, 10.4	Initial and periodic performance checks of roof monitor effluent gas characterization apparatus.	Ensure accurate and precise measurement of roof monitor effluent gas temperature and flow rate.
11.0	Interference/recovery efficiency check during distillation.	Minimize negative effects of used acid.

9.2 Volume Metering System Checks. Same as Method 5, Section 9.2.

10.0 Calibration and Standardization

Same as Section 10.0 of either Method 13A or Method 13B, as applicable, with the addition of the following:

10.1 Manifold Intake Nozzles. The manifold intake nozzles shall be calibrated when the manifold system is installed or, alternatively, the manifold may be preassembled

and the nozzles calibrated on the ground prior to installation. The following procedures shall be observed:

10.1.1 Adjust the exhaust fan to draw a volumetric flow rate (refer to Equation 14–1) such that the entrance velocity into each manifold nozzle approximates the average effluent velocity in the roof monitor.

10.1.2 Measure the velocity of the air entering each nozzle by inserting a standard pitot tube into a 2.5 cm or less diameter hole

(see Figure 14-2) located in the manifold between each blast gate (or valve) and nozzle. Note that a standard pitot tube is used, rather than a type S, to eliminate possible velocity measurement errors due to cross-section blockage in the small (0.13 m diameter) manifold leg ducts. The pitot tube tip shall be positioned at the center of each manifold leg duct. Take care to ensure that there is no leakage around the pitot tube, which could affect the indicated velocity in the manifold leg.

10.1.3 If the velocity of air being drawn into each nozzle is not the same, open or close each blast gate (or valve) until the velocity in each nozzle is the same. Fasten each blast gate (or valve) so that it will remain in position, and close the pitot port holes.

10.2 Initial Calibration of Propeller Anemometers.

10.2.1 Anemometers that meet the specifications outlined in Section 6.1.1 need not be calibrated, provided that a reference performance curve relating anemometer signal output to air velocity (covering the velocity range of interest) is available from the manufacturer. If a reference performance curve is not available from the manufacturer, such a curve shall be generated.

For the purpose of this method, a "reference" performance curve is defined as one that has been derived from primary standard calibration data, with the anemometer mounted vertically. "Primary standard" data are obtainable by: (a) direct calibration of one or more of the anemometers by the National Institute of Standards and Technology (NIST); (b) NIST-traceable calibration; or (c) Calibration by direct measurement of fundamental parameters such as length and time (*e.g.*, by moving the anemometers through still air at measured rates of speed, and recording the output signals).

10.2.2 Anemometers having output signals other than electrical (*e.g.*, optical) may be used, subject to the approval of the Administrator. If other types of anemometers are used, a reference performance curve shall be generated, using procedures subject to the approval of the Administrator.

10.2.3 The reference performance curve shall be derived from at least the following three points: 60 ± 15 , 900 ± 100 , and 1800 ± 100 rpm.

10.3 Initial Performance Checks. Conduct these checks within 60 days before the first performance test.

10.3.1 Anemometers. A performance-check shall be conducted as outlined in Sections 10.3.1.1 through 10.3.1.3. Alternatively, any other suitable method that takes into account the signal output, propeller condition, and threshold velocity of the anemometer may be used, subject to the approval of the Administrator.

10.3.1.1 Check the signal output of the anemometer by using an accurate rpm generator (see Figure 14-3) or synchronous motors to spin the propeller shaft at each of the three rpm settings described in Section 10.2.3, and measuring the output signal at each setting. If, at each setting, the output signal is within 5 percent of the manufacturer's value, the anemometer can be used. If the anemometer performance is unsatisfactory, the anemometer shall either be replaced or repaired.

10.3.1.2 Check the propeller condition, by visually inspecting the propeller, making note of any significant damage or warpage; damaged or deformed propellers shall be replaced.

10.3.1.3 Check the anemometer threshold velocity as follows: With the anemometer mounted as shown in Figure 14-4(A), fasten a known weight (a straight-pin will suffice) to the anemometer propeller at a fixed distance from the center of the propeller shaft. This will generate a known torque; for example, a 0.1-g weight, placed 10 cm from the center of the shaft, will generate a torque of 1.0 g-cm. If the known torque causes the propeller to rotate downward, approximately 90° [see Figure 14-4(B)], then the known torque is greater than or equal to the starting torque; if the propeller fails to rotate approximately 90°, the known torque is less than the starting torque. By trying different combinations of weight and distance, the starting torque of a particular anemometer can be satisfactorily estimated. Once an estimate of the starting torque has been obtained, the threshold velocity of the anemometer (for horizontal mounting) can be estimated from a graph such as Figure 14-5 (obtained from the manufacturer). If the horizontal threshold velocity is acceptable [<15 m/min (50 ft/min), when this technique is used], the anemometer can be used. If the threshold velocity of an anemometer is found to be unacceptably high, the anemometer shall either be replaced or repaired.

10.3.2 Recorders and Counters. Check the calibration of each recorder and counter (see Section 6.1.2) at a minimum of three points, approximately spanning the expected range of velocities. Use the calibration procedures recommended by the manufacturer, or other suitable procedures (subject to the approval of the Administrator). If a recorder or counter is found to be out of calibration by an average amount greater than 5 percent for the three calibration points, replace or repair the system; otherwise, the system can be used.

10.3.3 Temperature Measurement Apparatus. Check the calibration of the Temperature Measurement Apparatus, using the procedures outlined in Section 10.3 of Method 2, at temperatures of 0, 100, and 150 °C (32, 212, and 302 °F). If the calibration is off by more than 5 °C (9 °F) at any of the temperatures,